## MOTOR PROTECTOR WITH AMPEREMETER, GROUND FAULT AND OUTPUT $4-20 \mathrm{~mA}$, CONTROL BOARD SEPARATE

## Descripción

- MCU(Micro Controller Unit) based.
- Base module and control board separate.
- Wide functions range, easy to program.
- Three integral current transformers.
- Multiple protection functions.
- Wide current range protection from 0.1A to 3600A only a model.
- Current display:
- Order display: $\mathrm{L} 1 \rightarrow \mathrm{~L} 2 \rightarrow \mathrm{~L} 3 \rightarrow \mathrm{GF} \rightarrow \mathrm{L} 1 \rightarrow \ldots$.
- Display time of each current is 5 sec., user can select the phase to read manually.
- Time-Current trip characteristics selectable (see tables 2 and 3 ):
- Overcurrent protection / Ground fault protection.
- Thermal memory protection (see table 3).
- Non-thermal memory protection (see table 2).
- Digital amperemeter integrated.
- Total running time display.
- Overload trip bar graph control.
- 4-20mA current loop communications.
- Test function.
- Fail safe selection / Version without voltage (FS : ON)
- Wide room temperature range working.


## I/O Terminals Configuration

| $\begin{gathered} \text { 85~250V } \\ \text { resplen } \end{gathered}$ | OL |  |  | GR$\stackrel{\rightharpoonup}{\circ}$ |  | ZCT |  | 4~20mA |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A1 A2 | $95 \mid 96$ | 97 | 98 | 57 | 58 | Z1 | Z2 | + |  |  |

## Typical Application Diagram



## Frontal configuration



## Function feature

| Protected Item | Operation Delay |
| :--- | :--- |
| Overcurrent | $1 \ldots .30 \mathrm{seC}$ (adjustable time) |
|  | Type $1 . . .30$ (inverse time) |
| Undercurrent | $1 \ldots .30 \mathrm{sec}$ (adjustable time) |
| Phase Loss | 3 sec. |
| Phase Reversal | $0,1 \mathrm{sec}$. |
| Unbalance | 8 sec. |
| Locked rotor/running | Trip after "dt" time (see "how to set") |
| Locked rotor/work | $1 \ldots . .10$ sec. (see "how to set") |
| Ground fault | $0,05 \ldots 10$ sec. (adjustable time) |

## How to setup

## 1) Current:

- Definite time - Set the rated motor current in "OC" mode. For protection of connected machinery with motor, it is recommended to set the $10 \sim 115 \%$ of running current after motor current is stabilized.
- Inverse time - 100\% of rated motor current or 110~125\% actual motor current is recommended.

2) D-Time: Set the expected run-up time of motor in "dt" mode.

## 3) O-Time :

- Definite Time - Set the desired trip delay time in "ot" mode.
- Inverse Time - Set the trip delay time according to Time-Current characteristics.


## How to set

| Mode | ( + ON | Search a mode to be adjusted by depressing UP/DN mode switch. |
| :---: | :---: | :---: |
| Set | SET | Selected mode and setting value start flickering which means to be ready to accept setting as depressing once a Set/store button. |
| Adjust | $\text { ( } \underset{O N}{\square}$ | Select a required setting value and/or characters by depressing continuously UP/DN mode switch until reaching what want to do. |
| Store | SET | Store a selected value and/or characters by depressing once Set/store button. Instantaneously the flickering is stopped. |
| Reset | RESET | After completing above procedure, make a reset to be ready to operate. If not made reset, it will be reset automatically after an elapse of 30 sec . |
| Current rotation by Manual |  | Instead of automatic rotation, manual display rotation is possible as depressing once SET/ Store button during an operation. If manual is selected, the information of phase current L1 is displayed firstly and next information is displayed continuously like a manner of: $\mathrm{L} 1 \rightarrow \mathrm{~L} 2 \rightarrow \mathrm{~L} 3 \rightarrow \mathrm{GF} \rightarrow \mathrm{L} 1 \rightarrow \ldots$. |

## Size



Table 1

| Current set- <br> ting range (A.) | Number of conduc- <br> tors through CT | External CT <br> Ratio | Setting of <br> CT Ratio | Remark |
| :---: | :---: | :---: | :---: | :---: |
| $0.5 \ldots . .60 \mathrm{~A}$ | 1 | - | OFF (Mode:--) | Wide Range |
| $0.25 \ldots 3.0 \mathrm{~A}$ | 2 | - | 2 t |  |
| $0.1 \ldots 1.2 \mathrm{~A}$ | 5 | - | 5 t |  |
| $1 \ldots . .12 \mathrm{~A}$ | 1 | $10: 5$ | 10 |  |
| $1.5 \ldots 18 \mathrm{~A}$ | 1 | $15: 5$ | 15 |  |
| $2.0 \ldots 24 \mathrm{~A}$ | 1 | $20: 5$ | 20 |  |
| $2.5 \ldots 30 \mathrm{~A}$ | 1 | $25: 5$ | 25 |  |
| $3.0 \ldots 36 \mathrm{~A}$ | 1 | $30: 5$ | 30 |  |
| $4.0 \ldots 48 \mathrm{~A}$ | 1 | $40: 5$ | 40 |  |
| $5 \ldots 60 \mathrm{~A}$ | 1 | $50: 5$ | 50 |  |
| $6 \ldots . .72 \mathrm{~A}$ | 1 | $60: 5$ | 60 |  |
| $7.5 \ldots 90 \mathrm{~A}$ | 1 | $75: 5$ | 75 |  |
| $10 \ldots .120 \mathrm{~A}$ | 1 | $100: 5$ | 100 |  |
| $12 \ldots .144 \mathrm{~A}$ | 1 | $120: 5$ | 120 |  |
| $15 \ldots . .180 \mathrm{~A}$ | 1 | $150: 5$ | 150 |  |
|  |  |  |  |  |

## Table 2

| Current set- <br> ting range (A.) | Number of conduc- <br> tors through CT | External CT <br> Ratio | Setting of <br> CT Ratio | Remark |
| :---: | :---: | :---: | :---: | :---: |
| $20 \ldots . .240 \mathrm{~A}$ | 1 | $200: 5$ | 200 |  |
| $25 \ldots 300 \mathrm{~A}$ | 1 | $250: 5$ | 250 |  |
| $30 \ldots 360 \mathrm{~A}$ | 1 | $300: 5$ | 300 |  |
| $40 \ldots 480 \mathrm{~A}$ | 1 | $400: 5$ | 400 |  |
| $50 \ldots 600 \mathrm{~A}$ | 1 | $500: 5$ | 500 |  |
| $60 \ldots 720 \mathrm{~A}$ | 1 | $600: 5$ | 600 |  |
| $75 \ldots 900 \mathrm{~A}$ | 1 | $750: 5$ | 750 |  |
| $80 \ldots 960 \mathrm{~A}$ | 1 | $800: 5$ | 800 |  |
| $100 \ldots 1200 \mathrm{~A}$ | 1 | $1000: 5$ | 1000 |  |
| $120 \ldots 1440 \mathrm{~A}$ | 1 | $1200: 5$ | 1200 |  |
| $150 \ldots 1800 \mathrm{~A}$ | 1 | $1500: 5$ | 1500 |  |
| $200 \ldots 2400 \mathrm{~A}$ | 1 | $2000: 5$ | 2000 |  |
| $250 \ldots 3000 \mathrm{~A}$ | 1 | $2500: 5$ | 2500 |  |
| $300 \ldots 3600 \mathrm{~A}$ | 1 | $3000: 5$ | 3000 |  |

## Table 3



Table 2. OC adjustable time features


Table 3. OC inverse time features 0.5...10A / combined with external transformer

## Trip Display

| Function | LED Display | Description |
| :---: | :---: | :---: |
| Overload |  | Tripped by over current |
| Uncerload |  | Tripped by under current |
| Locked rotor running | - LC- | Tripped by Locked Rotor |
| Locked rotor work |  | Locked Rotor in running |
| Phase reversal |  | Tripped by Phase reversal |
| Phase unbalance |  | Tripped by unbalance phase |
| Phase loss |  | Tripped by phase loss |
| Ground fault | : $-E C-:$ | Tripped by fround fault current |

